

Jaykumar Goswami

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EDUCATION

Northeastern University	Boston, MA
<i>Master of Science - Robotics (Concentration: Electrical and Computer Engineering)</i>	<i>September 2024 – May 2026</i>
Birla Vishvakarma Mahavidyalaya	Gujarat, India
<i>Bachelor of Technology - Electronics Engineering (Grant-In-Aid) - CGPA: 8.20/10</i>	<i>July 2019 – June 2023</i>

TECHNICAL SKILLS

Robotics and Automation:	ROS, Linux, PID Control, AMR & ASRS Development , CODESYS, PLC & HMI Systems, , Digital Twin , IIoT, KEPserverEX, ThingWorx
Electronics Systems:	Sensors and Actuators Integration, Custom PCB Design , Circuit Design, Microcontrollers, Embedded System Design
Designing and Prototyping:	CAD Modeling (Fusion 360 , SolidWorks), 3D printing (SLA and FDM), 3D scanning, CNC machining, FEM analysis, Topology Optimization
Programming Languages:	C/C++, C#, Python , MATLAB

EXPERIENCE

Junior Research Fellow (JRF)	August 2023 – August 2024
<i>Birla Vishvakarma Mahavidyalaya, Digital Manufacturing Lab</i>	<i>Gujarat, India</i>
<ul style="list-style-type: none">Developed a 360kg capacity Automated Storage and Retrieval System, ensuring industry-grade standards.Led the development of an industry grade Autonomous Mobile Robot (AMR) with 1500kg loading capacity for international manufacturing company, reducing manual handling by 60%.Created a smart training manufacturing kit for students and machine operators with PLC, HMI, and I/O link.Enabled advanced process monitoring and better control using PTC ThingWorx & KEPserverEX.Worked on a 14 degrees of freedom (DoF) biped robot, simulating and replicating human walking patterns and designed custom PCBs for specialized DC motors with encoders.	
Summer Intern	July 2023 – July 2023
<i>Ural Federal University (UrFU)</i>	<i>Yekaterinburg, Russia</i>
<ul style="list-style-type: none">Conceptualized a bio-inspired robot gripper for the cake production industry.Reduced weight of the gripper by 40% and improved production line efficiency by 25% through FEM analysis and topology optimization. Simulated the whole assembly line using ABB Robot Studio.	
Researcher	December 2022 – June 2023
<i>Space Application Centre - ISRO</i>	<i>Gujarat, India</i>
<ul style="list-style-type: none">Built a digital twin model of a thermo-vacuum chamber and quantum payload using AR/VR and IoT technology, enhancing real-time monitoring and analysis capabilities by 50%.Successfully developed software to visualize payload temperature and pressure data, and created an IoT-enabled AR mobile app for real-time status monitoring. Accessible via ISRO's internal network using unique user credentials.	
Robotics Instructor	September 2022 – October 2023
<i>BrightChamps - Ed-Teach Company</i>	<i>Karnataka, India</i>
<ul style="list-style-type: none">Taught robotics to international students aged 8 to 16 via online mode, delivering high-quality education and fostering a passion for technology.	

PUBLICATIONS

Research Papers and Patent
<ul style="list-style-type: none">Jay Goswami, Vinay Patel, Mehfuza Holia, Ashish Thakkar (December 2023) <i>"Unity-Based Digital Twin for 3D Printers: Bridging the Gap Between Virtual and Physical Realities."</i> Presented at Women in Science and Technology International Conference.Jai G. Singla, Jay Goswami, Keivalya Pandya, Darshan K. Patel, Vinay Patel, Mehfuza Holia (June 2023) <i>"Application of Digital Twin in Space Engineering Using Augmented Reality and Internet of Things Technology."</i> Published in Current Science Journal (Indexed by Scopus).Design Patent (No: 356336-001) of <i>"IoT Enabled Smart Upper Prosthetic Limb"</i> Granted by Government of India.